



Autonomy and AI

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AI: Recent Developments

- Driven by advances in machine learning
 - Deep learning; Big data; Commodity hardware (e.g GPUs, AI processors)
- Strong impact in image recognition, speech understanding, automated translation
- Rapid expansion in other fields
 - Natural sciences, social sciences, engineering, medicine
- Strong investments in industry
 - Google, Facebook, Microsoft, Apple, Samsung, Intel, Adobe
- International expansion (Canada, Europe, China)
- Strong educational demand: undergraduate and graduate



AI at University of Maryland

- Integral part of “Computing at UMD” since 1960s
- Strong research groups in computer vision, natural language processing, planning and game theory
- Recent growth in machine learning, robotics, data science
- Strong interest all over the campus
 - STEM fields (natural sciences, engineering)
 - Non-STEM fields (social sciences, humanities, business)



AI at University of Maryland

- Computer vision
- Neuro and swarm computing
- Robotics
- Machine learning
- Natural language processing



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One of the Oldest and Largest Vision Groups in the World

- Founded by Azriel Rosenfeld in 1965.
- By quantitative measures (csrankings.org) #2 group in US, 1998-2018.
- Five computer vision faculty (Aloimonos, Chellappa, Davis, Jacobs, Shrivastava)
- Plus several research faculty (Castillo, Chen, Fermuller, Yacoob),
- Other related faculty (eg., Daume, Duraiswami, Goldstein, Samet, Zwicker),
- ~60 grad students



High Impact Research

- Rosenfeld led foundational work in many early areas of CV, including Relaxation Labeling (3000+ cites).
- Active Vision (1600+ cites), seminal paper in key area of vision.
- Visual Invariants (series of papers launched this subfield of CV).
- Discriminant Analysis for Face Recognition (2000+ cites); remain world leaders in FR.
 - Invention of the year (2 times); work led to FR startup.
- Non-parametric background subtraction (series of 4 papers with 7500+ citations).
- Leafsnap (First app to use CV for species ID, 1.5m downloads, extensive media coverage).
- 10s of millions in funding.

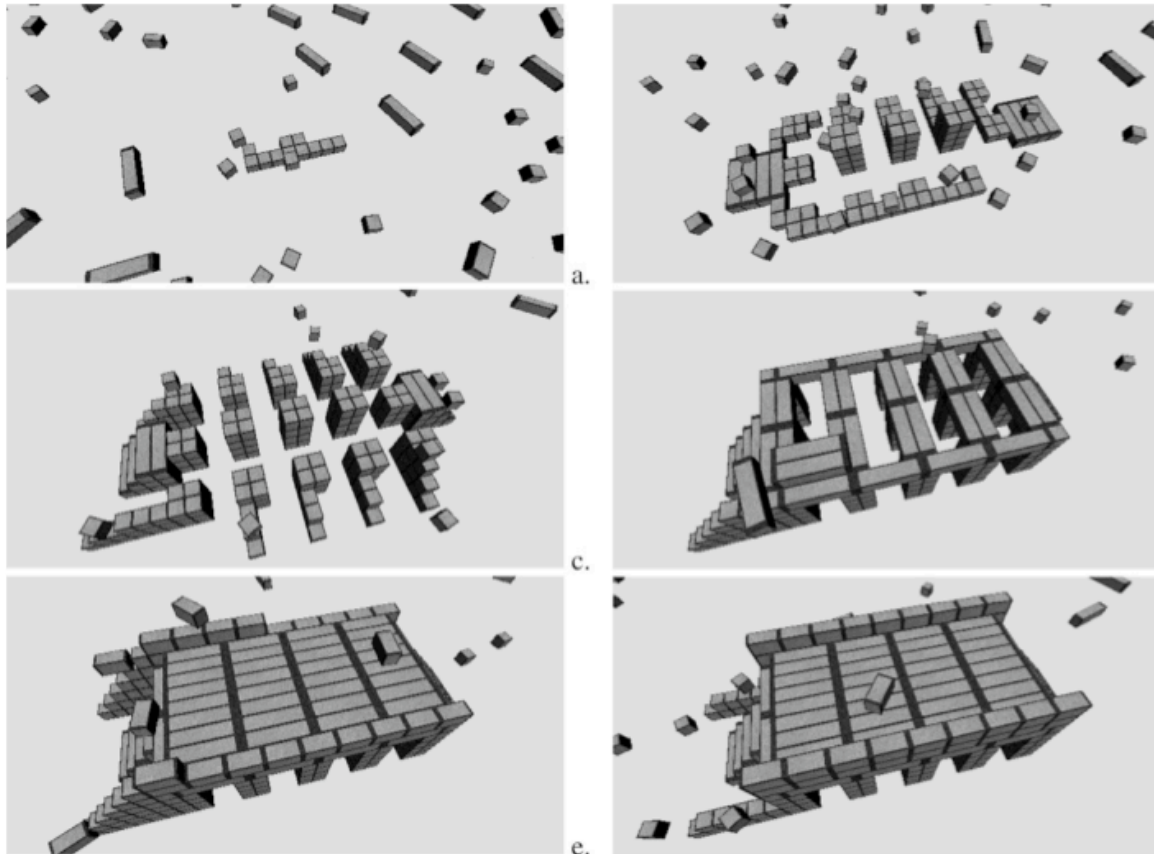


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- **Neuro and swarm computing**
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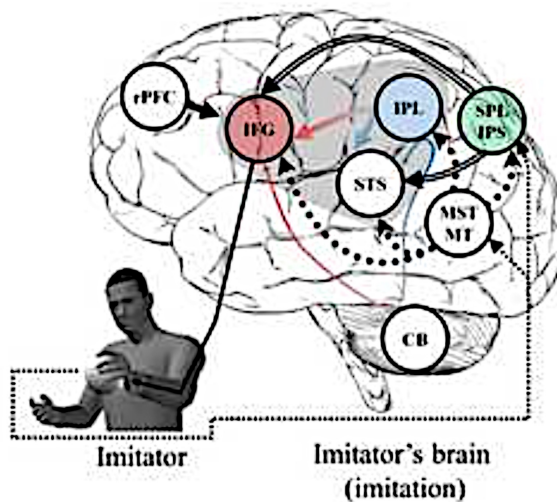
Swarm Intelligence



Example:
self-assembly
of components
into complex
structures
(bridge here)

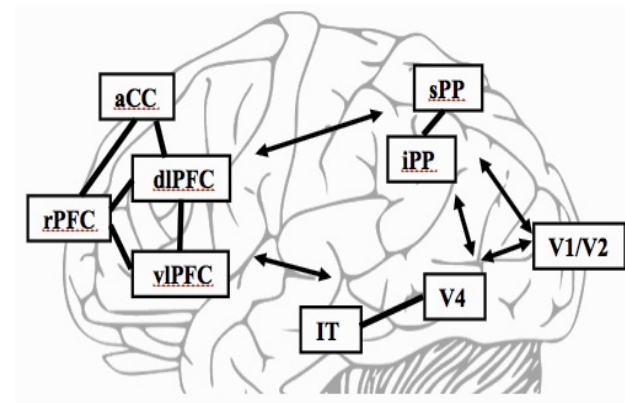
Grushin A, et al., *ACM Trans. Autonomous and Adaptive Systems*, 5, 2010.

Large-Scale Neurocognitive Architectures



imitation learning

Oh H, et al.. *Human Movement Science*, 2018, in press.



cognitive control

Sylvester J, et al.. *Neural Networks*, 79, 2016, 37-52.



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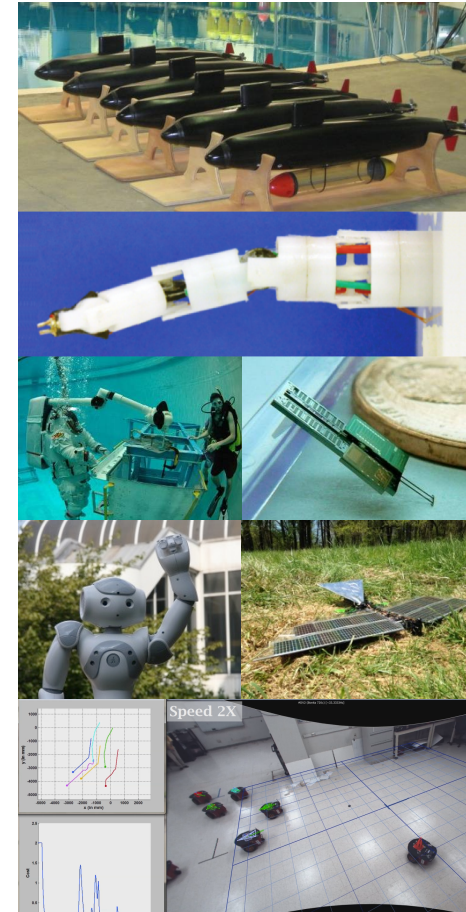
Maryland Robotics Center: Overview

- Housed in the Institute for Systems Research
- Consists of twenty-one labs
- Consists of 40 participating faculty members from eight academic departments
- Current activities cover most facets of robotics
- Educational programs including M. Eng in Robotics

Center Research Expertise

- Bio-Inspired Robotics
- Cognitive Robotics
- Cooperative, Collaborative, Networked Robotics
- Unmanned Vehicles
- Miniature Robots
- Medical Robotics
- Robotics in Extreme Environments
- Social Robotics

Center research projects are supported by the major federal funding agencies including NSF, ARO, ARL, ONR, AFOSR, NIH, DARPA, NASA, and NIST.





AI at University of Maryland

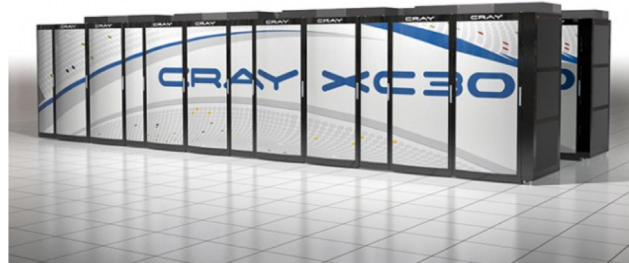
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Machine Learning

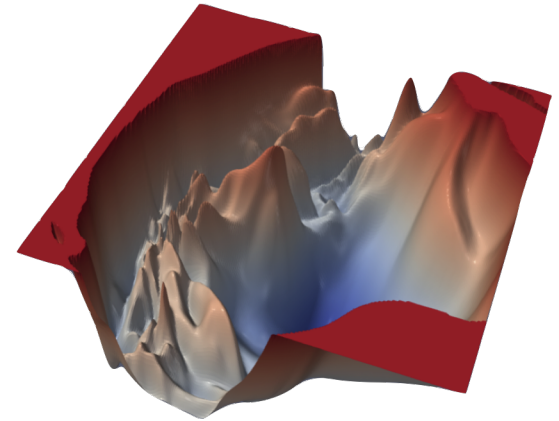


Research Areas

Distributed ML for
big data in the cloud



Understanding Neural
Nets



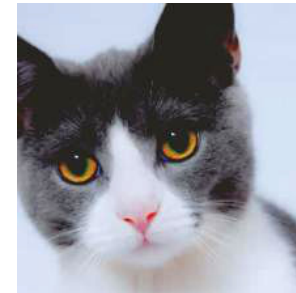
ML on portable
low-power devices

- Optimization
- Distributed computing
- Computer vision
- Circuit design



Adversarial Learning

“cat”



“traffic light”

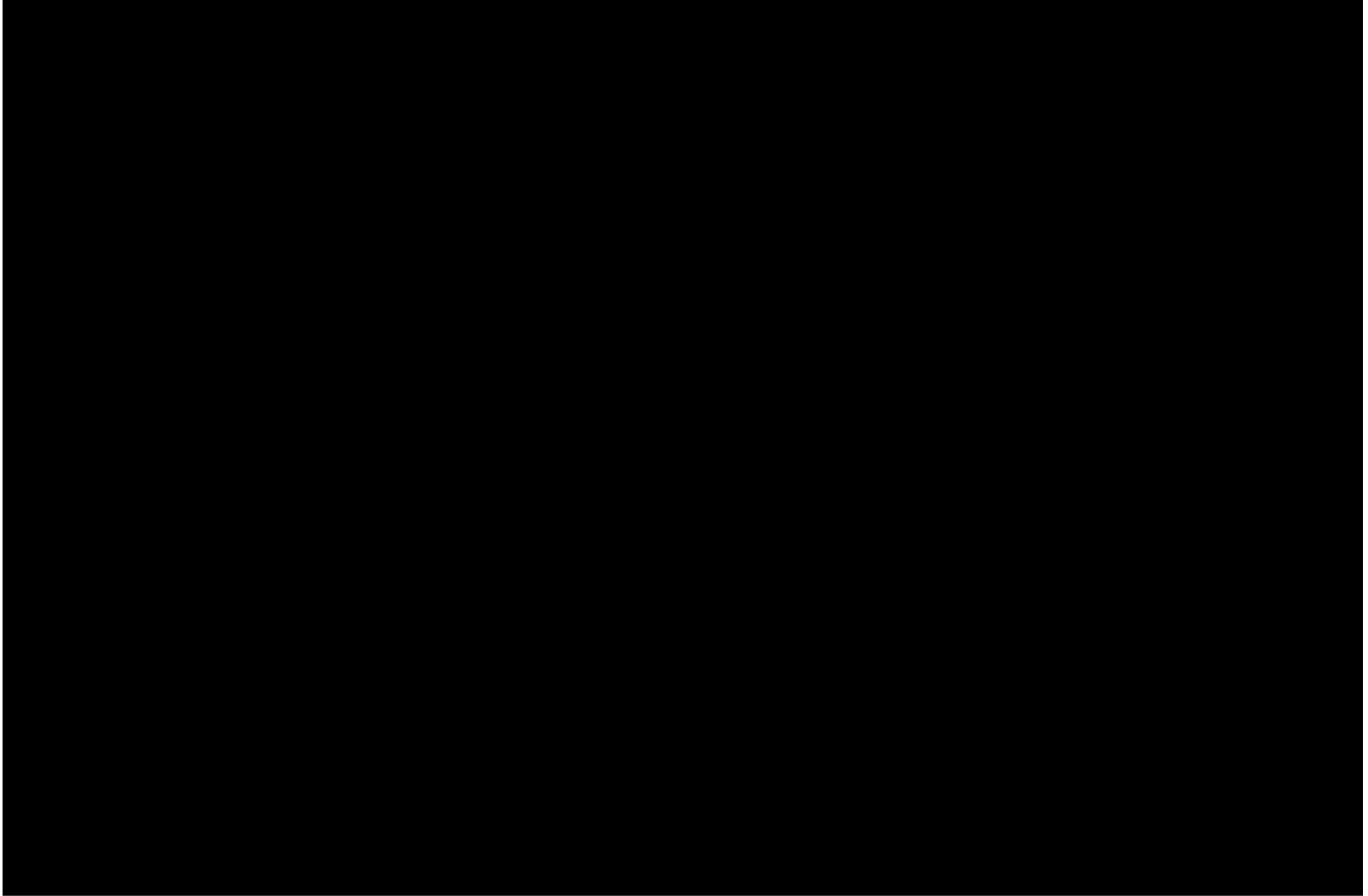


Real Robot Demo

7-DOF Fetch robot arm

Dynamic motion planning
with/without human motion
prediction

Natural Language Human-Robot Communication



Robots and Crowds: Realtime Navigation



Automatic navigation
General environments
No precomputation
Simple Lidar sensor

Current AD technology vs. Real-world Scenarios



- Many traffic situations are still too challenging for autonomous vehicles



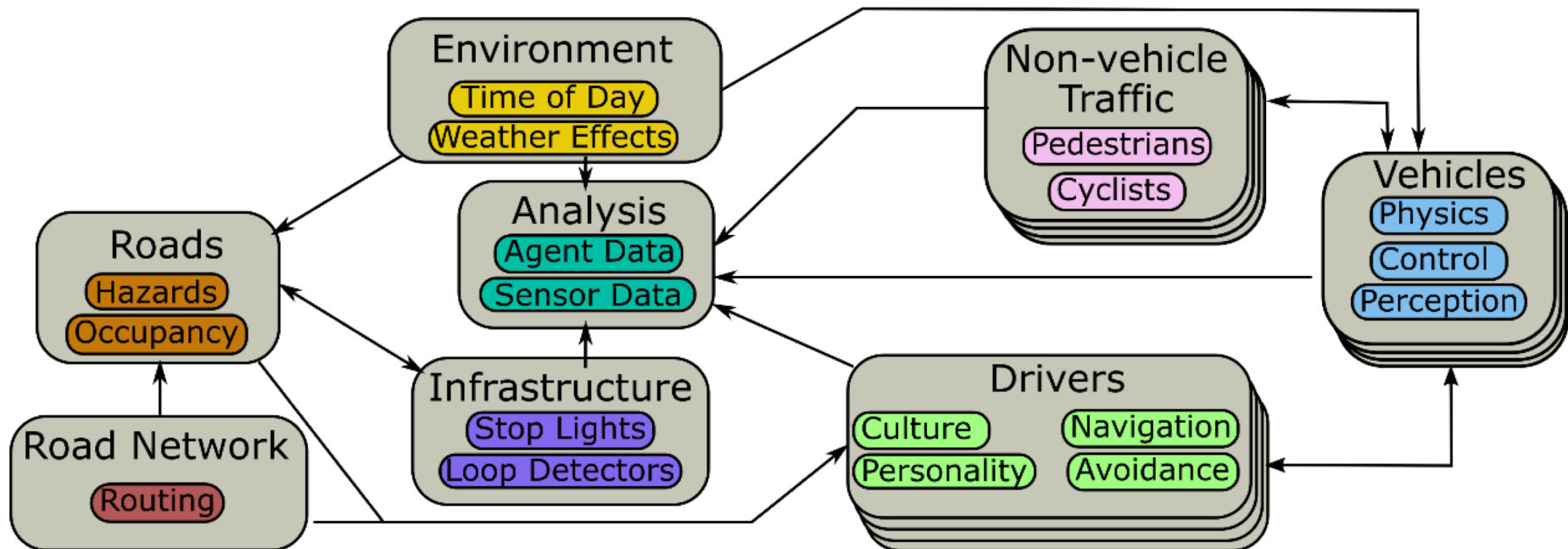
Current Autonomous Driving



Urban Traffic Condition

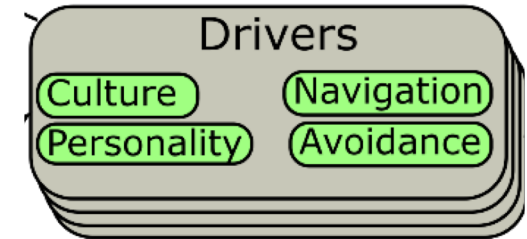
Autonovi-Sim

- Modular simulation framework for generating dynamic traffic conditions, weather, driver profiles, and road networks
- Facilitates novel driving strategy development
- On top of Unreal Engine



Autonovi-Sim: Drivers

- 3 Drivers in AutoNoVi-Sim
 - Manual
 - Basic Follower
 - AutoNoVi



RealTime Traffic Tracking



Agents: Cars, Scooters, Bicycles, Rickshaws, Pedestrians, Animals

Car: **Green**

Rickshaws: **Purple**

Pedestrians & Two-Wheelers: **Red**

Buses: **Cyan**

Animals: **Yellow**

Realtime Traffic Prediction



Predicting trajectory of different road-agents; cars, bicycles, pedestrians